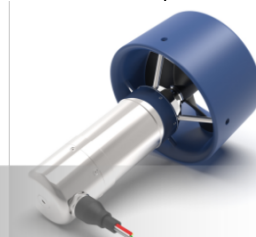


# UNDERWATER THRUSTER

## D4835

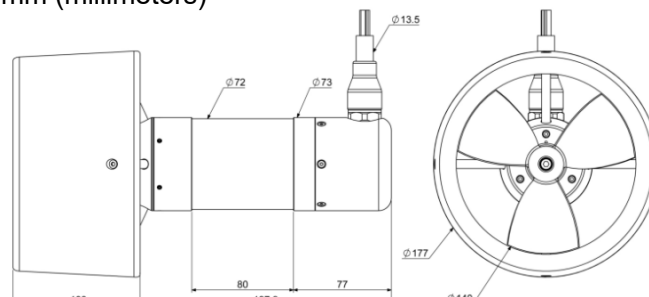
DREAM SERIES |D Series



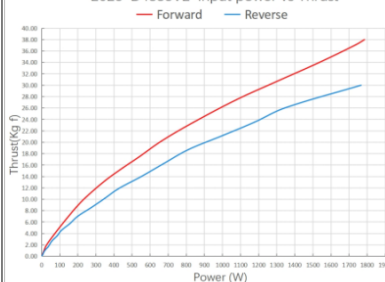
### Parameter Introduction

- Motor type: Internal rotor brushless motor
- Operating Voltage: 48 V DC (supports wide voltage range of 38 V to 54 V)
- Rated thrust: Front 35 Kg/Back 28.5 Kg
- Rated power: 1600 W
- Rated speed: 2550 rpm
- Working water depth: ≤300 m
- Control signal: PWM/CAN dual throttle
- Communication method: CAN bus (provides communication protocols)
- Feedback data: Speed, current, temperature, drive board status, fault code
- Drive type: Built-in FOC drive
- Protection mechanisms: Overcurrent, overheating, undervoltage, locked rotor
- Sealing method: Bidirectional hydraulic balanced rotary seal (Maintenance interval: 1000 hours of cumulative operating time or 1 year, depending on the propeller's operational condition)
- Shell material: 316L stainless steel
- Propeller material: Aluminum alloy/316L stainless steel (customizable)
- Propeller configuration: CW/CCW
- Flow guide cover material: POM
- Cable material: TPU (polyether polyurethane)
- Cable specifications: Outer diameter 13.5 mm, length 1.5 m, core 2x6 mm<sup>2</sup>+ 2x2x22 AWG
- Temperature: Storage: -10°C to 40°C; Working: -5°C to 37°C
- Cable weight: Net weight 6000 g, Water weight 4275 g

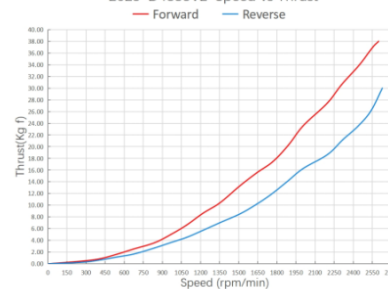
Unit: mm (millimeters)



2025-D4835V2-Input power vs Thrust



2025-D4835V2-Speed vs Thrust



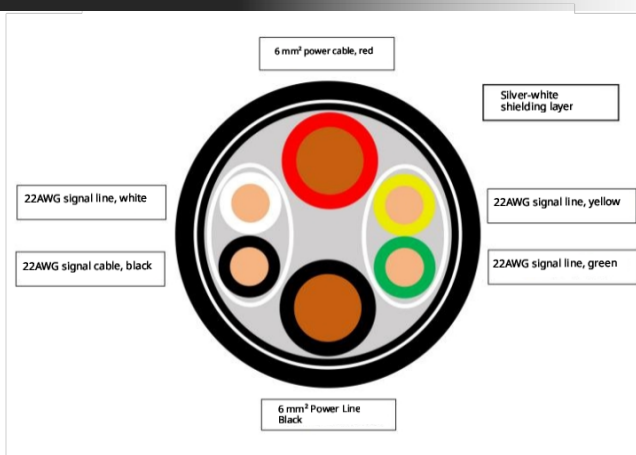
### Wiring Definition and Control

This product is shipped with the wires exposed at the terminal connections.

- Number of conductors: 6 + 1 core
- Power Line Group: Red V+, Black V-
- PWM Signal Lines: White (S), Black (GND)
- CAN bus group: Yellow H, Green L
- Shield layer group: Silver circle identifier
- Precautions for shielding layer wiring: It must be connected in parallel with the GND of the PWM signal group.

#### Control Precautions:

- The PWM input control signal is: 1.0 ms (maximum backward push) ~ 1.5 ms (stop position) ~ 2.0 ms (maximum forward push)
- When PWM input control is used, the CAN bus serves solely for data reading.
- When using CAN bus control, keep the PWM input pin floating.
- When operating in PWM control mode, switching to CAN control requires a complete power cycle; the mode selected during power-on shall prevail.



### User Instructions, Storage, and Transportation

Read carefully to avoid non-standard usage that may result in policy cancellation.

- Do not use the device under overvoltage conditions or with reversed polarity connections, as this may cause the propulsion unit to burn out.
- The underwater propeller is specifically designed for subaquatic use and must be fully submerged during operation to ensure efficient heat dissipation.
- After continuous operation exceeding 1000 hours, maintenance must be performed (including paid replacement of the original factory-made dynamic seal assembly). Failure to replace it promptly may result in water leakage or motor burnout; once damaged or leaking, the motor cannot be maintained.**
- Do not operate in air or highly turbid sediment. **Continuous idle operation in air should not exceed 10 seconds** to prevent seal damage, water ingress, or motor burnout due to poor motor heat dissipation.
- The maximum operating water depth must not exceed 300 m; otherwise, the propeller will fail.
- Do not reverse for extended periods to prevent propeller failure.
- For enhanced after-sales service and a superior product experience, both the flow guide cover and propeller of this product are replaceable spare parts available for purchase.
- This product is a high-speed rotating power device equipped with blades. During operation, the propeller must be kept away from any foreign objects or body parts.
- The aircraft body is made of stainless steel and has passed extensive salt spray testing, ensuring its durability in seawater environments.
- For the cable section, avoid excessive bending to prevent internal breakage of the conductor.
- The wiring of the underwater propeller must comply with the "Wiring Specifications"; failure to do so may damage the propeller's drive circuit.
- It should be stored in a cool, dry, and well-ventilated location, protected from direct sunlight, and kept away from fire and high temperatures.
- If the underwater propeller has been stored for an extended period in sub-zero, icy conditions, it should first be thawed at room temperature before use.
- During transportation, the maximum temperature of underwater propellers must remain below 50°C, and they must not be subjected to heavy loads during transit.

Both functional and intriguing; craftsmanship is refined in the heart.

**RHINCODON**® Rike Shield